

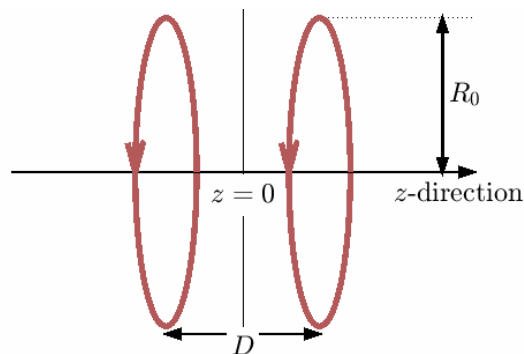


Basic Physics Course with MATLAB's Symbolic Toolbox and Live Editor

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6.2 Helmholtz coil (Computational example)

A Helmholtz coil arrangement consists of two current-carrying conductor rings in the same direction on a common axis. For an optimal homogeneous magnetic field between the coils, we must choose the coil radius and distance equal ($R_0 = D$).



We calculate the magnetic field lines in the x-z plane, plot them, and compare them to the experiment.

$$\text{Vector potential: } \vec{A}(\vec{R}) = \frac{1}{c} \int \vec{j}(\vec{r}) \frac{1}{|\vec{R} - \vec{r}|} d^3r$$

$$\text{Current: } \vec{j}(\vec{r}) = J \hat{e}_\phi \delta(r - R_0) \left(\delta\left(z - \frac{R_0}{2}\right) + \delta\left(z + \frac{R_0}{2}\right) \right)$$

Parameter: $R_0 = J = c = 1$

```
clear all
syms z J G jv
syms r R R0 Z phi Phi positive
Par=[R0==1 J==1]
```

```
Par = (R0 = 1 J = 1)
```

1 Basic vectors in cylinder coordinates

$$\vec{r} = \begin{pmatrix} r \cos \varphi \\ r \sin \varphi \\ z \end{pmatrix}, \quad \vec{R} = \begin{pmatrix} R \cos \Phi \\ R \sin \Phi \\ Z \end{pmatrix}, \quad \hat{e}_\varphi = \frac{1}{r} \frac{\partial}{\partial \varphi} \vec{r}$$

$$\text{rv} = [r * \cos(\text{phi}); r * \sin(\text{phi}); z]$$

rv =

$$\begin{pmatrix} r \cos(\varphi) \\ r \sin(\varphi) \\ z \end{pmatrix}$$

$$\text{Rv} = [R * \cos(\text{Phi}); R * \sin(\text{Phi}); Z]$$

Rv =

$$\begin{pmatrix} R \cos(\Phi) \\ R \sin(\Phi) \\ Z \end{pmatrix}$$

$$\text{e_phi} = \text{diff}(\text{rv}, \text{phi}) / r$$

e_phi =

$$\begin{pmatrix} -\sin(\varphi) \\ \cos(\varphi) \\ 0 \end{pmatrix}$$

2 Vector potential

$$\text{Vector potential: } \vec{A}(\vec{R}) = \frac{1}{c} \int \vec{j}(\vec{r}) \frac{1}{|\vec{R} - \vec{r}|} r dr d\varphi dz$$

$$\text{Current } \vec{j}(\vec{r}) = J \hat{e}_\varphi \delta(r - R_0) \left(\delta\left(z - \frac{R_0}{2}\right) + \delta\left(z + \frac{R_0}{2}\right) \right)$$

$$\text{jv} = J * \text{e_phi} * \text{dirac}(r - R_0) * (\text{dirac}(z - R_0/2) + \text{dirac}(z + R_0/2))$$

jv =

$$\begin{pmatrix} -J \sin(\varphi) \delta(R_0 - r) \left(\delta\left(\frac{R_0}{2} - z\right) + \delta\left(\frac{R_0}{2} + z\right) \right) \\ J \cos(\varphi) \delta(R_0 - r) \left(\delta\left(\frac{R_0}{2} - z\right) + \delta\left(\frac{R_0}{2} + z\right) \right) \\ 0 \end{pmatrix}$$

$$\text{Propagator } G = \frac{1}{|\vec{r} - \vec{R}|}$$

$$G=1/\text{simplify}(\text{norm}(r\mathbf{v}-R\mathbf{v}))$$

G =

$$\frac{1}{\sqrt{|Z - z|^2 + (R \cos(\Phi) - r \cos(\varphi))^2 + (R \sin(\Phi) - r \sin(\varphi))^2}}$$

Potential without integration $\vec{A}^{(\varphi)} = \int \vec{j} G r dr dz$, $\vec{A} = \int \vec{A}^{(\varphi)} d\varphi$

$$A_{\mathbf{v}}_{\text{phi}} = \text{int}(\text{int}(r * \mathbf{j}_{\mathbf{v}} * G, r, \theta, \text{inf}), z, -\text{inf}, \text{inf})$$

A_v_phi =

$$\begin{pmatrix} -\frac{J R_0 \sin(\varphi)}{\sigma_1} - \frac{J R_0 \sin(\varphi)}{\sigma_2} \\ \frac{J R_0 \cos(\varphi)}{\sigma_1} + \frac{J R_0 \cos(\varphi)}{\sigma_2} \\ 0 \end{pmatrix}$$

where

$$\sigma_1 = \sqrt{\left| \frac{R_0}{2} - Z \right|^2 + (R \cos(\Phi) - R_0 \cos(\varphi))^2 + (R \sin(\Phi) - R_0 \sin(\varphi))^2}$$

$$\sigma_2 = \sqrt{(R \cos(\Phi) - R_0 \cos(\varphi))^2 + (R \sin(\Phi) - R_0 \sin(\varphi))^2 + \left(\frac{R_0}{2} + Z \right)^2}$$

in the x-z plane ($\Phi = 0$) and with parameters:

$$A_{\mathbf{v}}_{\text{phi}} = \text{sube}(A_{\mathbf{v}}_{\text{phi}}, [\text{Phi} = 0 \text{ Par}])$$

A_v_phi =

$$\begin{pmatrix} -\frac{\sin(\varphi)}{\sigma_1} - \frac{\sin(\varphi)}{\sigma_2} \\ \frac{\cos(\varphi)}{\sigma_2} + \frac{\cos(\varphi)}{\sigma_1} \\ 0 \end{pmatrix}$$

where

$$\sigma_1 = \sqrt{\sin(\varphi)^2 + (R - \cos(\varphi))^2 + \left|Z - \frac{1}{2}\right|^2}$$

$$\sigma_2 = \sqrt{\left(Z + \frac{1}{2}\right)^2 + \sin(\varphi)^2 + (R - \cos(\varphi))^2}$$

3 x and z component of the vector potential

$$A_x = \int_0^{2\pi} A_1^{(\varphi)} d\varphi, \quad A_z = \int_0^{2\pi} A_3^{(\varphi)} d\varphi$$

```
A_x=int(Av_phi(1),phi,0,2*pi)
```

```
A_x = 0
```

```
A_z=int(Av_phi(3),phi,0,2*pi)
```

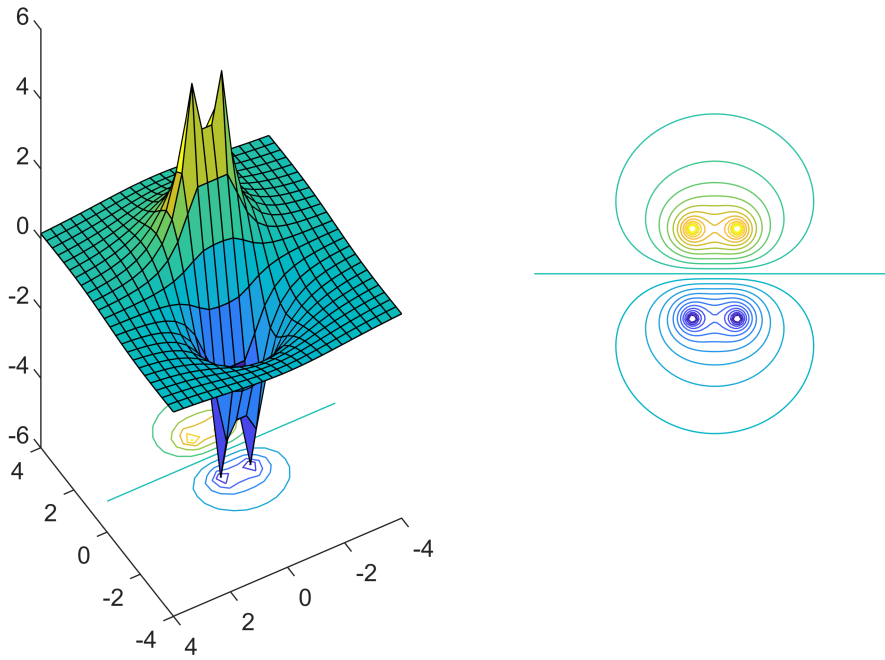
```
A_z = 0
```

4 y component A_y with field lines (see also appendix below)

$$A_y = \int_0^{2\pi} A_2^{(\varphi)} d\varphi$$

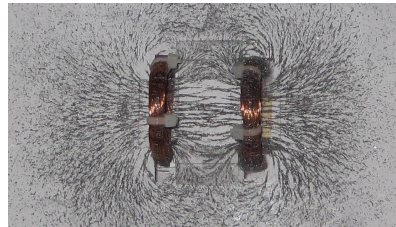
```
[Rn,Zn,Ayn]=GetAy(Av_phi(2),24);
subplot(1,2,1)
hold on
surfc(Rn,Zn,Ayn);
axis([-4 4 -4 4 -6 6])
view([-120.2 25.0])

[Rn,Zn,Ayn]=GetAy(Av_phi(2),100);
subplot(1,2,2)
contour(Zn,Rn,Ayn,6*linspace(-1,1,25))
axis equal
axis off
```



Comparison with the experiment:

Helmholtz coil and iron filings on a glass plate

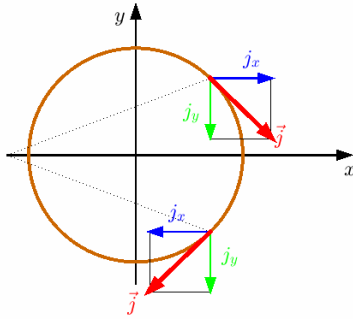


Appendix: Field lines for Helmholtz coil in the z-x plane

$$\text{Vector potential: } \vec{A}(\vec{R}) = \frac{1}{c} \int \vec{j}(\vec{r}) \frac{1}{|\vec{R} - \vec{r}|} d^3r$$

$$\text{Current: } \vec{j}(\vec{r}) = J \hat{e}_\phi \delta(r - R_0) \left(\delta\left(z - \frac{R_0}{2}\right) + \delta\left(z + \frac{R_0}{2}\right) \right)$$

Helmholtz coil and current components j :



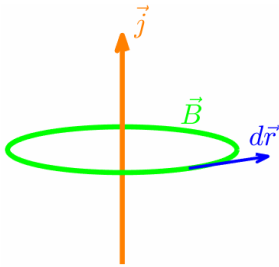
From symmetry considerations follows $A_x = A_z = 0$:

Vector potential z - x - plane: $\vec{A}(x, 0, z) = A_y(x, z)\hat{e}_y$

$A_z(x, z) = 0$: \vec{j} has no z-component!
 $A_x(x, z) = 0$: $j_x(x, y, z) = -j_x(x, -y, z)$

The magnetic field lines in the z-x plane can be represented as contour lines of the vector potential A_y :

Field lines:



$$\begin{aligned}
 \underbrace{0 = \vec{B} \times d\vec{r}}_{\text{Conditional equations}} &= \begin{pmatrix} B_y dz - B_z dy \\ B_z dx - B_x dz \\ B_x dy - B_y dx \end{pmatrix} = \begin{pmatrix} \left(\frac{\partial A_y}{\partial z} - \frac{\partial A_z}{\partial x} \right) dz - \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) dy \\ \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) dx - \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) dz \\ \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) dy - \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) dx \end{pmatrix} \\
 &= \left(\frac{\partial A_y(x, z)}{\partial x} dx + \frac{\partial A_y(x, z)}{\partial z} dz \right) \hat{e}_y = dA_y(x, z)\hat{e}_y = 0
 \end{aligned}$$

Function for φ -integration (numerical)

```

function [Rn,Zn,Ayn]=GetAy(Ay_phi,N)
[Rn,Zn]=meshgrid(linspace(-4,4,N));
Ay_phim=matlabFunction(Ay_phi);
Ayn=integral(@(phi)Ay_phim(Rn,Zn,phi),0,2*pi,'ArrayValued',true);
end

```