



Basic Physics Course with MATLAB's Symbolic Toolbox and Live Editor

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6.4 Radiation of the Hertzian dipole (Computational example)

A Hertzian dipole consists of a negative point charge at the coordinate origin and a harmonic-moving positive point charge at $\vec{a}(t)$.

Trajectory of the positive charge: $\vec{a}(t) = a_0 \cos(\omega t) \hat{e}_z$

Charge density: $\rho(\vec{r}, t) = q(\delta(\vec{r} - \vec{a}(t)) - \delta(\vec{r}))$

Current: $\vec{j}(\vec{r}, t) = \vec{v}(\vec{r}, t)\rho(\vec{r}, t) = q\dot{\vec{a}}(t)\delta(\vec{r} - \vec{a}(t))$

Vector potential: $\vec{A}(\vec{r}, t) = \frac{\mu_0}{4\pi} \int dt' d^3\vec{r}' \frac{\vec{j}(\vec{r}', t') \delta(t - c^{-1}|\vec{r} - \vec{r}'| - t')}{|\vec{r} - \vec{r}'|}$

Parameter: $a_0 = q = \mu = \omega = c = 1$

```
clear all
syms r t tb a0 q av positive
syms theta phi omega mu c x z real

Par=[a0==1 q==1 mu==1 omega==1 c==1]
```

```
Par = (a0 = 1 q = 1 mu = 1 omega = 1 c = 1)
```

1 Spherical coordinates

Spherical coordinates: $\vec{r} = \begin{pmatrix} r \sin \theta \cos \varphi \\ r \sin \theta \sin \varphi \\ r \cos \theta \end{pmatrix}$

$$\text{Jacobian: } J = \left(\frac{\partial x_i}{\partial q_j} \right) = \left(\vec{g}_r, \vec{g}_\theta, \vec{g}_\varphi \right), \quad \rightarrow \quad \hat{e}_r = \frac{\vec{g}_r}{|\vec{g}_r|}, \hat{e}_\theta = \frac{\vec{g}_\theta}{|\vec{g}_\theta|}, \hat{e}_\varphi = \frac{\vec{g}_\varphi}{|\vec{g}_\varphi|}$$

$$\text{z-direction: } \hat{e}_z = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$r_v = [r \cdot \sin(\theta) \cdot \cos(\varphi); r \cdot \sin(\theta) \cdot \sin(\varphi); r \cdot \cos(\theta)]$$

r_v =

$$\begin{pmatrix} r \cos(\varphi) \sin(\theta) \\ r \sin(\varphi) \sin(\theta) \\ r \cos(\theta) \end{pmatrix}$$

$$J = \text{jacobian}(r_v, [r, \theta, \varphi]);$$

$$e_r = J(:, 1)$$

e_r =

$$\begin{pmatrix} \cos(\varphi) \sin(\theta) \\ \sin(\varphi) \sin(\theta) \\ \cos(\theta) \end{pmatrix}$$

$$e_theta = J(:, 2) / r$$

e_theta =

$$\begin{pmatrix} \cos(\varphi) \cos(\theta) \\ \cos(\theta) \sin(\varphi) \\ -\sin(\theta) \end{pmatrix}$$

$$e_phi = J(:, 3) / (r \cdot \sin(\theta))$$

e_phi =

$$\begin{pmatrix} -\sin(\varphi) \\ \cos(\varphi) \\ 0 \end{pmatrix}$$

$$E_z_xA = [0; 0; 1]$$

E_z_xA = 3x1

0
0
1

$$XPlane = [\varphi == 0 \quad \theta == \pi/2 \quad r == x]$$

XPlane =

$$\left(\varphi = 0 \quad \theta = \frac{\pi}{2} \quad r = x\right)$$

$$\text{XZPlane} = [\text{phi} == 0 \quad \text{sin}(\text{theta}) == x/r \quad \text{cos}(\text{theta}) == z/r \quad r == \text{sqrt}(x^2 + z^2)]$$

XZPlane =

$$\left(\varphi = 0 \quad \text{sin}(\theta) = \frac{x}{r} \quad \text{cos}(\theta) = \frac{z}{r} \quad r = \sqrt{x^2 + z^2}\right)$$

2 Vector potential in far field approximation

$$\text{Current of the Hertzian dipole: } \vec{j}(\vec{r}, t) = q \dot{\vec{a}}(t) \delta(\vec{r} - \vec{a}(t)) \xrightarrow{\text{far field approximation}} q \dot{\vec{a}}(t) \delta(\vec{r})$$

$$\begin{aligned} \text{Vector potential: } \vec{A}(\vec{r}, t) &= \frac{\mu_0}{4\pi} \int dt' d^3\vec{r}' \frac{\vec{j}(\vec{r}', t') \delta(t - c^{-1}|\vec{r} - \vec{r}'| - t')}{|\vec{r} - \vec{r}'|} \\ &\rightarrow \frac{\mu_0}{4\pi} \int dt' d^3\vec{r}' \frac{q \dot{\vec{a}}(t') \delta(\vec{r}') \delta(t - c^{-1}|\vec{r} - \vec{r}'| - t')}{|\vec{r} - \vec{r}'|} \\ &= \frac{\mu_0}{4\pi r} q \dot{\vec{a}}(t - r/c) = -\frac{\mu_0}{4\pi r} q \omega \sin(t - r/c) \hat{e}_z \end{aligned}$$

$$\text{A}_v = (-\mu_0 \omega q a_0 \sin(\omega(t - r/c)) / (4\pi r)) \hat{e}_z$$

A_v =

$$\begin{pmatrix} 0 \\ 0 \\ -\frac{a_0 \mu_0 \omega q \sin\left(\omega\left(t - \frac{r}{c}\right)\right)}{4\pi r} \end{pmatrix}$$

$$\text{in spherical coordinates basis: } \vec{A}^{(Ku)} = \begin{pmatrix} \vec{A} \cdot \hat{e}_r \\ \vec{A} \cdot \hat{e}_\theta \\ \vec{A} \cdot \hat{e}_\varphi \end{pmatrix}$$

$$\text{A}_Ku = [\text{dot}(\text{A}_v, \text{e}_r); \text{dot}(\text{A}_v, \text{e}_\theta); \text{dot}(\text{A}_v, \text{e}_\varphi)]$$

A_Ku =

$$\begin{pmatrix} -\frac{a_0 \mu \omega q \sin\left(\omega\left(t - \frac{r}{c}\right)\right) \cos(\theta)}{4 r \pi} \\ \frac{a_0 \mu \omega q \sin\left(\omega\left(t - \frac{r}{c}\right)\right) \sin(\theta)}{4 r \pi} \\ 0 \end{pmatrix}$$

3 B and E field in spherical coordinates basis

Magnetic field: $\vec{B}^{(Ku)} = \text{rot} \vec{A}^{(Ku)}$

Electric field: $\vec{E}^{(Ku)} = \int \text{rot} \vec{B}^{(Ku)} dt$

The curl in spherical coordinates is calculated with the function Curl3d at the end of this script.

$$B_Ku = \text{Curl3d}(A_Ku, [r, \theta, \phi], [1, r, r \cdot \sin(\theta)])$$

$B_Ku =$

$$\begin{pmatrix} 0 \\ 0 \\ \frac{a_0 \mu \omega q \sin(\theta) \left(c \sin\left(\frac{\omega(r - ct)}{c}\right) - \omega r \cos\left(\frac{\omega(r - ct)}{c}\right) \right)}{4 c r^2 \pi} \end{pmatrix}$$

$$E_Ku = \text{int}(\text{Curl3d}(B_Ku, [r, \theta, \phi], [1, r, r \cdot \sin(\theta)]), t)$$

$E_Ku =$

$$\begin{pmatrix} \frac{a_0 c \mu q \cos(\theta) \sigma_2 + a_0 \mu \omega q r \sigma_1 \cos(\theta)}{2 c r^3 \pi} \\ \frac{a_0 \mu q \sin(\theta) \sigma_2 (c^2 - \omega^2 r^2) + a_0 c \mu \omega q r \sigma_1 \sin(\theta)}{4 c^2 r^3 \pi} \\ 0 \end{pmatrix}$$

where

$$\sigma_1 = \sin\left(\frac{\omega(r - ct)}{c}\right)$$

$$\sigma_2 = \cos\left(\frac{\omega(r - ct)}{c}\right)$$

4 B and E on the x -axis

x-axis: $r = x, \theta = \frac{\pi}{2}, \varphi = 0$

E field: $\vec{E} = E_r^{(Ku)} \hat{e}_r + E_\theta^{(Ku)}$

B field: $\vec{B} = B_\varphi^{(Ku)} \hat{e}_\varphi$

`E_v=E_Ku(1)*e_r+E_Ku(2)*e_theta`

$E_v =$

$$\begin{pmatrix} \frac{\cos(\varphi) \cos(\theta) \sigma_1}{\sigma_3} + \frac{\cos(\varphi) \sin(\theta) \sigma_2}{\sigma_4} \\ \frac{\sin(\varphi) \sin(\theta) \sigma_2}{\sigma_4} + \frac{\cos(\theta) \sin(\varphi) \sigma_1}{\sigma_3} \\ \frac{\cos(\theta) \sigma_2}{\sigma_4} - \frac{\sin(\theta) \sigma_1}{\sigma_3} \end{pmatrix}$$

where

$$\sigma_1 = a_0 \mu q \sin(\theta) \cos\left(\frac{\omega (r - ct)}{c}\right) (c^2 - \omega^2 r^2) + a_0 c \mu \omega q r \sin\left(\frac{\omega (r - ct)}{c}\right) \sin(\theta)$$

$$\sigma_2 = a_0 c \mu q \cos(\theta) \cos\left(\frac{\omega (r - ct)}{c}\right) + a_0 \mu \omega q r \sin\left(\frac{\omega (r - ct)}{c}\right) \cos(\theta)$$

$$\sigma_3 = 4 c^2 r^3 \pi$$

$$\sigma_4 = 2 c r^3 \pi$$

on the x axis

`sube(E_v,XPlane)`

ans =

$$\begin{pmatrix} 0 \\ 0 \\ \frac{a_0 \mu q \cos\left(\frac{\omega (x - ct)}{c}\right) (\omega^2 x^2 - c^2) - a_0 c \mu \omega q x \sin\left(\frac{\omega (x - ct)}{c}\right)}{4 c^2 x^3 \pi} \end{pmatrix}$$

`E_z_xA=ans(3)`

$E_z_xA =$

$$\frac{a_0 \mu q \cos\left(\frac{\omega (x - ct)}{c}\right) (\omega^2 x^2 - c^2) - a_0 c \mu \omega q x \sin\left(\frac{\omega (x - ct)}{c}\right)}{4 c^2 x^3 \pi}$$

y component of the *B* field on the x axis

`B_v=B_Ku(3)*e_phi`

`B_v =`

$$\begin{pmatrix} -\frac{a_0 \mu \omega q \sin(\varphi) \sin(\theta) \sigma_1}{4 c r^2 \pi} \\ \frac{a_0 \mu \omega q \cos(\varphi) \sin(\theta) \sigma_1}{4 c r^2 \pi} \\ 0 \end{pmatrix}$$

where

$$\sigma_1 = c \sin\left(\frac{\omega (r - ct)}{c}\right) - \omega r \cos\left(\frac{\omega (r - ct)}{c}\right)$$

`sube(B_v,XPlane)`

`ans =`

$$\begin{pmatrix} 0 \\ \frac{a_0 \mu \omega q \left(c \sin\left(\frac{\omega (x - ct)}{c}\right) - \omega x \cos\left(\frac{\omega (x - ct)}{c}\right) \right)}{4 c x^2 \pi} \\ 0 \end{pmatrix}$$

`B_y_xA=ans(2)`

`B_y_xA =`

$$\frac{a_0 \mu \omega q \left(c \sin\left(\frac{\omega (x - ct)}{c}\right) - \omega x \cos\left(\frac{\omega (x - ct)}{c}\right) \right)}{4 c x^2 \pi}$$

5 Graphics

```
R=linspace(0,20);
subplot(2,2,1)
hold on
plot3([0 20],[0 0],[0 0],':k')
B_y_xAM=matlabFunction(sube(B_y_xA,Par))
```

`B_y_xAM = function_handle with value:`

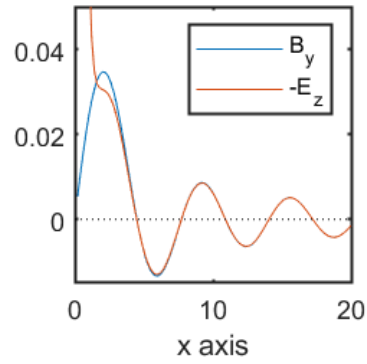
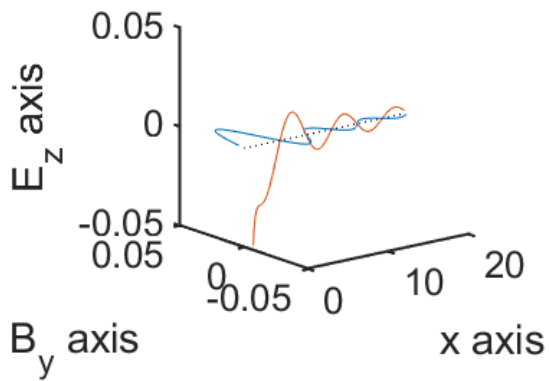
```
@(t,x)(1.0./x.^2.*(sin(t-x)+x.*cos(t-x)).*(-1.0./4.0))./pi
```

```
plot3(R,B_y_xAM(0,R),0*R)  
E_z_xAM=matlabFunction(sube(E_z_xA,Par))
```

E_z_xAM = function_handle with value:

```
@(t,x)(1.0./x.^3.*(cos(t-x).*(x.^2-1.0)+x.*sin(t-x)).*(1.0./4.0))./pi
```

```
plot3(R,0*R,E_z_xAM(0,R))  
axis([0 20 -.05 .05 -.05 .05])  
view([-74 23])  
axis square  
xlabel('x axis')  
ylabel('B_y axis')  
zlabel('E_z axis')  
hold off  
subplot(2,2,2)  
plot(R,B_y_xAM(0,R),R,-E_z_xAM(0,R),[0 20],[0 0],':k')  
axis([0 20 -0.015 0.05])  
xlabel('x axis')  
axis square  
legend('B_y','-E_z')  
  
subplot(2,2,1)  
view([-38.673 15.726])  
subplot(2,2,2)  
view([0.00 90.00])
```



6 Field lines of the E field in the x - z plane

The electric field lines can be plotted in the x - z plane as contour lines of the magnetic field integrated over time:

in the x - z plane: $B_x = 0, B_z = 0,$

Field lines:

$$0 = \underbrace{\vec{E} \times d\vec{r}}_{\left(\int \text{rot } \vec{B} dt\right) \times d\vec{r}} = \int \begin{pmatrix} \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} \\ \frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \\ \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \end{pmatrix} dt \times \begin{pmatrix} dx \\ 0 \\ dz \end{pmatrix} = \int \begin{pmatrix} 0 \\ \left(\frac{\partial B_y}{\partial x} + \frac{\partial B_y}{\partial z}\right) dz \\ 0 \end{pmatrix} dt = d \int \vec{B} dt \Big|_{x-z \text{ plane}}$$

B_v

B_v =

$$\begin{pmatrix} -\frac{a_0 \mu \omega q \sin(\varphi) \sin(\theta) \sigma_1}{4 c r^2 \pi} \\ \frac{a_0 \mu \omega q \cos(\varphi) \sin(\theta) \sigma_1}{4 c r^2 \pi} \\ 0 \end{pmatrix}$$

where

$$\sigma_1 = c \sin\left(\frac{\omega (r - ct)}{c}\right) - \omega r \cos\left(\frac{\omega (r - ct)}{c}\right)$$

`sube(B_v,XZPlane)`

ans =

$$\begin{pmatrix} 0 \\ -\frac{a_0 \mu \omega q x (c \sin(\sigma_1) + \omega \cos(\sigma_1) \sqrt{x^2 + z^2})}{4 c \pi (x^2 + z^2)^{3/2}} \\ 0 \end{pmatrix}$$

where

$$\sigma_1 = \frac{\omega (ct - \sqrt{x^2 + z^2})}{c}$$

`B_yt_xzE=int(ans(2),t)`

B_yt_xzE =

$$\frac{a_0 \mu q x \cos(\sigma_1)}{4 \pi \sigma_2^{3/2}} - \frac{a_0 \mu \omega q x \sin(\sigma_1)}{4 c \pi \sigma_2}$$

where

$$\sigma_1 = \frac{\omega (ct - \sqrt{\sigma_2})}{c}$$

$$\sigma_2 = x^2 + z^2$$

`B_yt_xzEM=matlabFunction(sube(B_yt_xzE,Par))`

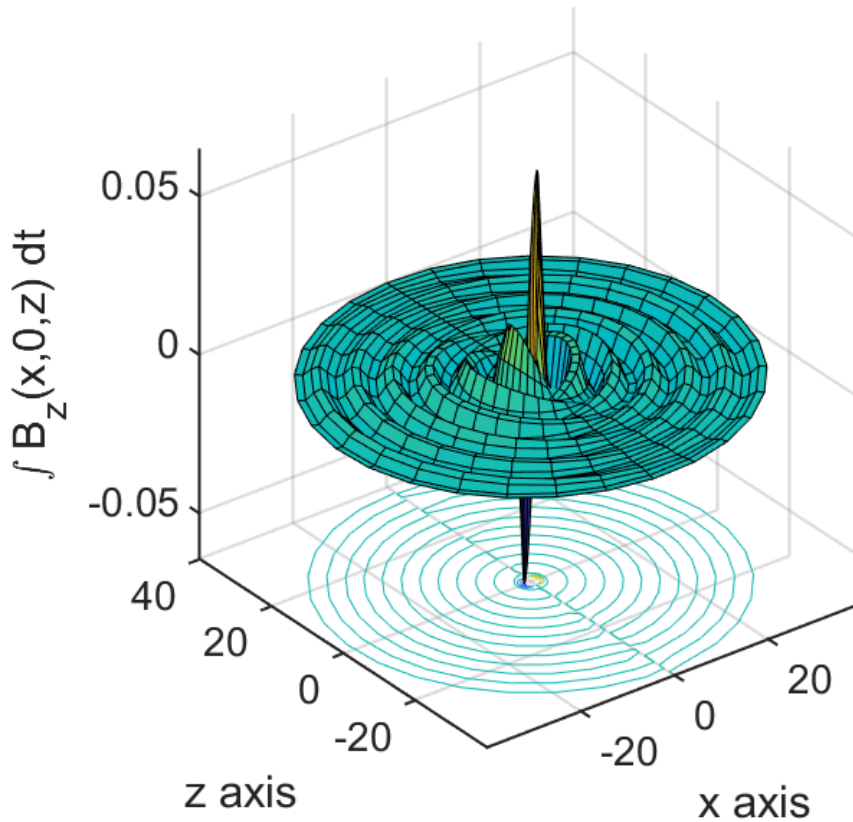
B_yt_xzEM = function_handle with value:

$$@ (t,x,z) (x.*\sin(t-\text{sqrt}(x.^2+z.^2)).*(-1.0./4.0))./(\text{pi}.*(x.^2+z.^2))+(x.*\cos(t-\text{sqrt}(x.^2+z.^2)).*1.0./ (x.^2+z.^2))$$

N=30

N = 30

```
[R,The]=meshgrid(linspace(0,40,N),linspace(0,2*pi,N));
X=R.*sin(The);
Z=R.*cos(The);
subplot(1,1,1)
surfc(X,Z,B_yt_xzEM(0,X,Z))
axis square
xlabel('x axis')
ylabel('z axis')
zlabel('\int{ B_z(x,0,z) dt}')
```



7 Animation of the field lines in the x-z plane (-> Hertz_Dipol.gif)

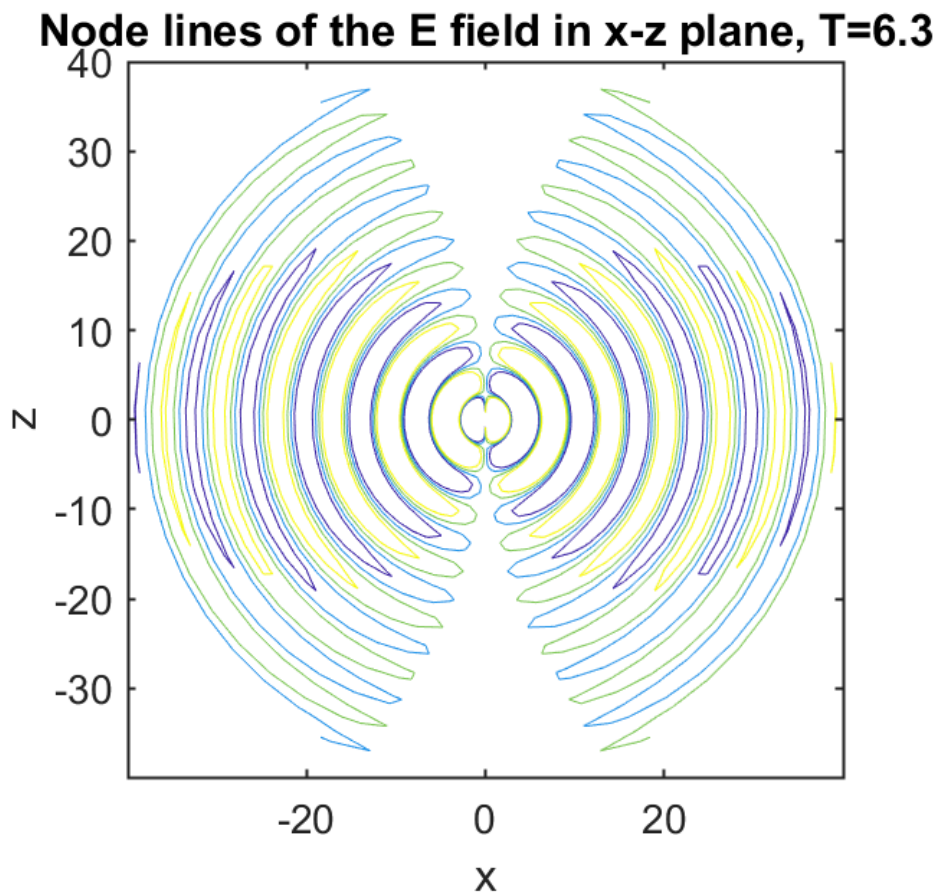
```
N=50;
[R,The]=meshgrid(linspace(0,40,N),linspace(0,2*pi,N));
X=R.*sin(The);
Z=R.*cos(The);

subplot(1,1,1)
clear im1
N=50;
T=linspace(0,2*pi,N);
n=1;
```

```

contour(X,Z,B_yt_xzEM(T(n),X,Z),0.002*linspace(-1,1,4))
axis square
xlabel('x')
ylabel('z')
title(sprintf('Node lines of the E field in x-z plane, T=%2f',T(n)))
im{n}=frame2im(getframe(gcf));
for n=1:size(T,2)
    contour(X,Z,B_yt_xzEM(T(n),X,Z),0.002*linspace(-1,1,4))
    axis square
    xlabel('x')
    ylabel('z')
    title(sprintf('Node lines of the E field in x-z plane, T=%2.1f',T(n)))
    im{n}=frame2im(getframe(gcf));
end

```



```

FiNa='Hertz_Dipol.gif';
n=1;
[A,map] = rgb2ind(im{n},8);
imwrite(A,map,FiNa,'gif','LoopCount',Inf,'DelayTime',0);
for n=2:size(T,2)
    [A,map]=rgb2ind(im{n},8);
    imwrite(A,map,FiNa,'gif','WriteMode','append','DelayTime',0);
end

```

Curl in generalized coordinates (function)

```
function Res=Curl3d(Ex,Ko,Me)
% Curl in generalized coordinates
% (Expression F,coordinates q, metric g)
```

$$\hat{e}_1(\vec{\nabla} \times \vec{F}) = \frac{1}{g_2 g_3} \left(\frac{\partial}{\partial q^2} g_3 F_3 - \frac{\partial}{\partial q^3} g_2 F_2 \right) \quad (\text{cyclical}), \quad g_i \equiv \left| \frac{\partial \vec{r}}{\partial q^i} \right|, \quad F_i \equiv \vec{F} \cdot \hat{e}_i$$

```
Res=[...
    1/(Me(2)*Me(3))*(diff(Me(3)*Ex(3,1),Ko(2))-diff(Me(2)*Ex(2,1),Ko(3)));...
    1/(Me(3)*Me(1))*(diff(Me(1)*Ex(1,1),Ko(3))-diff(Me(3)*Ex(3,1),Ko(1)));...
    1/(Me(1)*Me(2))*(diff(Me(2)*Ex(2,1),Ko(1))-diff(Me(1)*Ex(1,1),Ko(2)))...
    ];
Res=simplify(Res);
end
```