PROBABILISTIC MACHINE LEARNING Lecture 23 Free Energy

> Philipp Hennig 12 July 2021

# EBERHARD KARLS UNIVERSITÄT TÜBINGEN



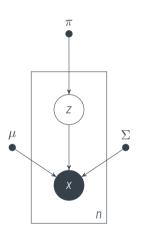
Faculty of Science Department of Computer Science Chair for the Methods of Machine Learning

# EM for Gaussian Mixtures

re-written in generic form

▶ Want to maximize, as function of  $\theta := (\pi_j, \mu_j, \Sigma_j)_{j=1,...,k}$ 

$$\log p(x \mid \pi, \mu, \Sigma) = \sum_{i} \log \left( \sum_{j} \pi_{j} \mathcal{N}(x_{i}; \mu_{j}, \Sigma_{j}) \right)$$





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# EM for Gaussian Mixtures

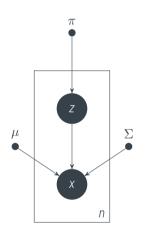
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$$\log p(x \mid \pi, \mu, \Sigma) = \sum_{i} \log \left( \sum_{j} \pi_{j} \mathcal{N}(x_{i}; \mu_{j}, \Sigma_{j}) \right)$$

▶ Instead, maximizing the "complete data" likelihood is easier:

$$\log p(x, z \mid \pi, \mu, \Sigma) = \log \prod_{i}^{n} \prod_{j}^{k} \pi_{j}^{z_{ij}} \mathcal{N}(x_{i}; \mu_{j}, \Sigma_{j})^{z_{ij}}$$
$$= \sum_{i} \sum_{j} Z_{nk} \underbrace{(\log \pi_{j} + \log \mathcal{N}(x_{i}; \mu_{j}, \Sigma_{j}))}_{\text{easy to optimize (exponential families)}}$$





re-written in generic form



## 1. Compute $p(z \mid x, \theta)$ :

$$p(z_{ij} = 1 \mid x_i, \pi, \mu, \Sigma) = \frac{p(z_{ij} = 1)p(x_i \mid z_{ij} = 1)}{\sum_{j'}^k p(z_{ij'} = 1)p(x_i \mid z_{ij'} = 1)} = \frac{\pi_j \mathcal{N}(x_i; \mu_j, \Sigma_j)}{\sum_{j'} \pi_j \mathcal{N}(x_i; \mu_j, \Sigma_j)} =: r_{ij}$$

#### 2. Maximize

$$\mathbb{E}_{p(z|x,\theta)}\left(\log p(x,z \mid \theta)\right) = \sum_{i} \sum_{j} r_{ij} \left(\log \pi_{j} + \log \mathcal{N}(x_{i};\mu_{j},\Sigma_{j})\right)$$

(see earlier slides on how to solve this, much easier problem)

Maximize **expected** log likelihoods



#### Setting:

▶ Want to find maximum likelihood (or MAP) estimate for a model involving a latent variable

$$\theta_* = \arg\max_{\theta} \left[\log p(x \mid \theta)\right] = \arg\max_{\theta} \left[\log \left(\sum_{z} p(x, z \mid \theta)\right)\right]$$

- > Assume that the summation inside the log makes analytic optimization intractable
- but that optimization would be analytic if z were known (i.e. if there were only one term in the sum) **Idea:** Initialize  $\theta_0$ , then iterate between
  - 1. Compute  $p(z \mid x, \theta_{old})$
  - 2. Set  $\theta_{new}$  to the Maximum of the Expectation of the *complete-data* log likelihood:

$$\theta_{\text{new}} = \arg \max_{\theta} \sum_{z} p(z \mid x, \theta_{\text{old}}) \log p(\underbrace{x, z}_{I} \mid \theta) = \arg \max_{\theta} \mathbb{E}_{p(z \mid x, \theta_{\text{old}})} \left[ \log p(x, z \mid \theta) \right]$$

3. Check for convergence of either the log likelihood, or  $\theta$ .



## The EM algorithm Instead of trying to maximize

$$\log p(x \mid \theta) = \log \sum_{z} p(x, z \mid \theta) = \log \sum_{z} p(z \mid x, \theta) p(x \mid \theta),$$

instead maximize

$$\mathbb{E}_{z} \log p(x, z \mid \theta) = \sum_{z} p(z \mid x, \theta) \log p(x, z \mid \theta),$$

then re-compute  $p(z \mid x, \theta)$ , and repeat.

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An Observation maximizing a lower bound

• We constructed an approximate distribution  $q(z) = p(z \mid x, \theta)$  for our latent quantity

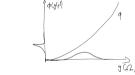
 $\log p(x \mid \theta) = \log \int p(x, z \mid \theta) dz \qquad = \log \int q(z) \frac{p(x, z \mid \theta)}{q(z)} dz$ 

For any such approximation q(z) (if q(z) > 0 wherever  $p(x, z | \theta) > 0$ ):

 $\geq \int q(z) \log \frac{p(x, z \mid \theta)}{q(z)} dz =: \mathcal{L}(q)$ 

Let  $(\Omega, A, \mu)$  be a probability space, g be a real-valued,  $\mu$ -integrable function and  $\phi$  be a convex function on the real line. Then

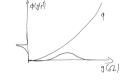
$$\phi\left(\int_{\Omega} g\,d\mu\right) \leq \int_{\Omega} \phi\circ g\,d\mu.$$





- We constructed an approximate distribution  $q(z) = p(z \mid x, \theta)$  for our latent quantity
- For any such approximation q(z) (if q(z) > 0 wherever  $p(x, z | \theta) > 0$ ):

$$\log p(x \mid \theta) = \log \int p(x, z \mid \theta) \, dz \qquad = \log \int q(z) \frac{p(x, z \mid \theta)}{q(z)} \, dz$$
$$\geq \int q(z) \log \frac{p(x, z \mid \theta)}{q(z)} \, dz \qquad =: \mathcal{L}(q)$$



- Thus, by maximizing the RHS in  $\theta$  in the M-step, we increase a lower bound on the LHS (the target quantity)
- But can we be sure that this increases the LHS?
- To show that this is the case, we will now establish that the E-step makes the bound *tight* at the local θ.



$$\mathcal{L}(q) = \int q(z) \log \frac{p(x, z \mid \theta)}{q(z)} dz = \int q(z) \log \frac{p(z \mid x, \theta) \cdot p(x \mid \theta)}{q(z)} dz$$
$$= \int q(z) \log \frac{p(z \mid x, \theta)}{q(z)} dz + \log p(x \mid \theta) \int q(z) dz$$
thus  $\log p(x \mid \theta) = \mathcal{L}(q) - \int q(z) \log \frac{p(z \mid x, \theta)}{q(z)} = \mathcal{L}(q) + D_{\mathsf{KL}}(q || p(z \mid x, \theta))$ 

The Kullback-Leibler divergence satisfies

- $\blacktriangleright D_{\mathsf{KL}}(q\|p) \geq 0$
- $\blacktriangleright D_{\mathsf{KL}}(q\|p) = 0 \quad \Leftrightarrow q \equiv p$

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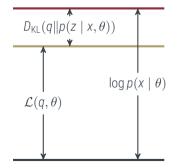
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# EM maximizes the ELBO / minimizes Free Energy

a more general view

$$\log p(x \mid \theta) = \mathcal{L}(q, \theta) + D_{\mathsf{KL}}(q \mid p(z \mid x, \theta))$$
$$\mathcal{L}(q, \theta) = \int q(z) \log \left(\frac{p(x, z \mid \theta)}{q(z)}\right) dz$$
$$D_{\mathsf{KL}}(q \mid p(z \mid x, \theta)) = -\int q(z) \log \left(\frac{p(z \mid x, \theta)}{q(z)}\right) dz$$



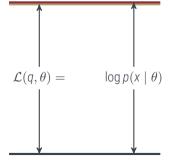


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E -step: 
$$q(z) = p(z \mid x, \theta_{old})$$
, thus  $D_{KL}(q \parallel p(z \mid x, \theta_i)) = 0$ 





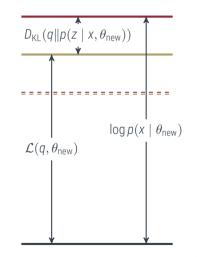
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E -step: 
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, thus  $D_{KL}(q || p(z \mid x, \theta_i)) = 0$   
M -step: Maximize ELBO

$$\theta_{\text{new}} = \arg \max_{\theta} \int q(z) \log p(x, z \mid \theta) \, dz$$
$$= \arg \max_{\theta} \mathcal{L}(q, \theta) + \int q(z) \log q(z) \, dz$$





for further generalization



#### Setting:

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1. Compute  $q(z) = p(z \mid x, \theta_{old})$ , thereby setting  $D_{KL}(q \parallel p(z \mid x, \theta)) = 0$ 

2. Set  $\theta_{new}$  to the Maximize the Evidence Lower Bound

$$\theta_{\mathsf{new}} = \arg\max_{\theta} \mathcal{L}(q, \theta) = \arg\max_{\theta} \int q(z) \log\left(\frac{p(x, z \mid \theta)}{q(z)}\right) \, dz$$

3. Check for convergence of either the log likelihood, or  $\theta$ .

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▶ If  $p(x, z | \theta)$  is an **exponential family** with  $\theta$  as the natural parameters, then

$$p(x,z) = \exp(\phi(x,z)^{\mathsf{T}}\theta - \log Z(\theta))$$
  

$$\mathcal{L}(q(z),\theta) = \mathbb{E}_{q(z)}(\phi(x,z)^{\mathsf{T}}\theta - \log Z(\theta)) = \mathbb{E}_{q(z)}[\phi(x,z)]^{\mathsf{T}}\theta - \log Z(\theta)$$
  

$$\nabla_{\theta}\mathcal{L}(q(z),\theta) = 0 \implies \nabla_{\theta}\log Z(\theta) = \mathbb{E}_{p(x,z)}[\phi(x,z)] = \mathbb{E}_{q(z)}[\phi(x,z)]$$

and optimization may be analytic (example: Gaussian Mixture Models).



## Some Observations

for future reference

It is straightforward to extend EM to maximize a posterior instead of a likelihood. Just add a log prior for θ:

Initialize  $\theta_0$ , then iterate between

- 1. Compute  $q(z) = p(z \mid x, \theta_{old})$ , thereby setting  $D_{KL}(q \parallel p(z \mid x, \theta)) = 0$
- 2. Set  $\theta_{new}$  to the Maximize the Evidence Lower Bound

$$\theta_{\text{new}} = \arg \max_{\theta} \int q(z) \log \left( \frac{p(x, z \mid \theta) p(\theta)}{q(z)} \right) \, dz = \arg \max_{\theta} \mathcal{L}(q, \theta) + \log p(\theta)$$

3. Check for convergence of either the log likelihood, or  $\theta$ . This maximizes

$$\log p(x \mid \theta) + \log p(\theta) \le \mathcal{L}(q, \theta) + \log p(\theta)$$
$$\triangleq \log p(\theta \mid x)$$



▶ When we set  $q(z) = p(z \mid x, \theta_{old})$ , we set  $D_{KL}$  to its minimum  $D_{KL}(q \parallel p(z \mid x, \theta) = 0$ , thus

$$\begin{aligned} \nabla_{\theta} \log p(x \mid \theta_{\text{old}}) &= \nabla_{\theta} \mathcal{L}(q, \theta_{\text{old}}) + \nabla_{\theta} D_{\text{KL}}(q \| p(z \mid x, \theta_{\text{old}})) \\ &= \nabla_{\theta} \mathcal{L}(q, \theta_{\text{old}}) \end{aligned}$$

So we could also use an optimizer based on this gradient to  $\mbox{numerically}$  optimize  $\mathcal L.$  This is known as  $\mbox{generalized EM}$ 



The EM algorithm:

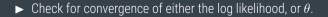
▶ to find *maximum likelihood* (or MAP) estimate for a model involving a latent variable

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M Set  $\theta_{new}$  to the Maximize the Expectation Lower Bound

$$\theta_{\mathsf{new}} = \arg\max_{\theta} \mathcal{L}(q, \theta) = \arg\max_{\theta} \sum_{z} q(z) \log\left(\frac{p(x, z \mid \theta)}{q(z)}\right)$$



The Toolbox



#### Framework:

$$\int p(x_1, x_2) \, dx_2 = p(x_1) \qquad p(x_1, x_2) = p(x_1 \mid x_2) p(x_2) \qquad p(x \mid y) = \frac{p(y \mid x) p(x_2)}{p(y)}$$

## Modelling:

- ► graphical models
- Gaussian distributions
- ► (deep) learnt representations
- ► Kernels
- Markov Chains
- Exponential Families / Conjugate Priors
- ► Factor Graphs & Message Passing

## Computation:

- ► Monte Carlo
- ► Linear algebra / Gaussian inference
- ► maximum likelihood / MAP
- ► Laplace approximations
- ► EM
- ►

The Toolbox



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- ► EM
- Variational Approximations



$$\log p(x \mid \theta) = \mathcal{L}(q, \theta) + D_{\mathsf{KL}}(q \| p(z \mid x, \theta))$$
$$\mathcal{L}(q, \theta) = \sum_{z} q(z) \log \left( \frac{p(x, z \mid \theta)}{q(z)} \right) \qquad D_{\mathsf{KL}}(q \| p(z \mid x, \theta)) = -\sum_{z} q(z) \log \left( \frac{p(z \mid x, \theta)}{q(z)} \right)$$

For EM, we minimized KL-divergence to find  $q = p(z \mid x, \theta)$  (E), then maximized  $\mathcal{L}(q, \theta)$  in  $\theta$ .

> What if we treated the parameters  $\theta$  as a probabilistic variable for full Bayesian inference?

$$Z \leftarrow Z \cup \theta$$

- ► Then we could just maximize  $\mathcal{L}(q(z))$  wrt. q (not z!) to implicitly minimize  $D_{KL}(q||p(z | x))$ , because log p(x) is constant. This is an **optimization in the space of distributions** q, not (necessarily) in parameters of such distributions, and thus a very powerful notion.
- ► In general, this will be intractable, because the optimal choice for q is exactly p(z | x). But maybe we can help out a bit with approximations. Amazingly, we often don't need to impose strong approximations. Sometimes we can get away with just imposing restrictions on the **factorization** of q, not its analytic form.



$$\log p(x) = \mathcal{L}(q) + D_{\mathsf{KL}}(q \| p(z \mid x))$$
$$\mathcal{L}(q) = \int q(z) \log \left(\frac{p(x, z)}{q(z)}\right) dz \qquad D_{\mathsf{KL}}(q \| p(z \mid x)) = -\int q(z) \log \left(\frac{p(z \mid x)}{q(z)}\right) dz$$

For EM, we minimized KL-divergence to find  $q = p(z \mid x, \theta)$  (E), then maximized  $\mathcal{L}(q, \theta)$  in  $\theta$ .

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ree energy / expectation lower bounds



#### Lemma

Consider the probability distribution p(x, z) and an arbitrary probability distribution q(z) such that q(z) > 0 whenever  $p(z) = \sum_{x} p(x, z) > 0$ . Then the following equality holds:

$$\log p(x) = \mathcal{L}(q(z)) + D_{KL}(q(z)||p(z \mid x))$$
  
where  $\mathcal{L}(q) := \int q(z) \log \left(\frac{p(x,z)}{q(z)}\right) dz$  and  $D_{KL}(q||p) := -\int q(z) \log \left(\frac{p(z \mid x)}{q(z)}\right) dz.$ 

 $\blacktriangleright$   $-\mathcal{L}(q)$  is known as the Variational Free Energy in physics, because

$$-\mathcal{L}(q) = -\mathbb{E}_q(\log p(x, z)) - \mathbb{H}(q) \quad \text{cf.} \quad F = U - TS$$

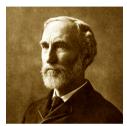
## Free Energy

Machine Learning is the application of scientific modelling to everything





Hermann v. Helmholtz 1821–1894 image:L. Meder "Energy"



Josia W. Gibbs 1839–1903 <sup>image:unknown</sup> "Enthalpy"

Ludwig Boltzmann

1844-1906

image:wikipedia

"Entropy"



David M. Blei

image:Denise Applewhite "Evidence"

 $\mathcal{F} = U - TS$ 

 $\mathcal{H} = U + pV$ 

 $\mathcal{G} = H - TS$ 

 $\mathcal{L} = \mathbb{E}_q(\log p(x, z)) + H(q)$ 



#### Variational Inference

► is a general framework to construct approximating probability distributions q(z) to non-analytic posterior distributions p(z | x) by minimizing the functional

$$q^* = rgmin_{q \in \mathcal{Q}} \mathcal{D}_{\mathit{KL}}(q(z) \| p(z \mid x)) = rgmax_{q \in \mathcal{Q}} \mathcal{L}(q)$$

# The Calculus of Variations

One of the big ideas they don't teach <u>you in school</u>





Leonhard Euler 1707–1783



Joseph-Louis Lagrange  
1736–1813  
$$\mathcal{L}(q) = \int q(z) \log\left(\frac{p(x,z)}{q(z)}\right)$$



## Richard P. Feynman 1918–1988 (Nobel Prize 1965)

# Factorizing Approximations

A surprisingly subtle approximation with strong implications



▶ in general, maximizing  $\mathcal{L}(q)$  wrt. q(z) is hard, because the extremum is exactly at  $q(z) = p(z \mid x)$ ▶ but let's assume that q(z) factorizes

$$q(z) = \prod_i q_i(z_i) = \prod_i^n q_i$$

 $\blacktriangleright$  then the bound simplifies. Let's focus on one particular variable  $z_j$ :

$$\begin{aligned} \mathcal{L}(q) &= \int \prod_{i}^{n} q_{i} \left( \log p(x, z) - \sum_{i} \log q_{i} \right) dz \\ &= \int q_{j} \left( \int \log p(x, z) \prod_{i \neq j} q_{i} dz_{i} \right) dz_{j} - \int q_{j} \log q_{j} dz_{j} + \text{const.} \\ &= \int q_{j} \log \tilde{p}(x, z_{j}) dz_{j} - \int q_{j} \log q_{j} dz_{j} + \text{const.} \\ \log \tilde{p}(x, z_{j}) &= \mathbb{E}_{q, i \neq j} [\log p(x, z)] + \text{const.} \end{aligned}$$

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where

# Mean Field Theory



Factorizing variational approximations

Consider a joint distribution p(x, z) with  $z \in \mathbb{R}^n$ 

- ▶ to find a "good" but tractable approximation q(z), assume that it factorizes  $q(z) = \prod_i q_i(z_i)$ .
- Initialize all  $q_i$  to some initial *distribution*
- Iteratively compute

$$\mathcal{L}(q) = \int q_j \log \tilde{p}(x, z_j) \, dz_j - \int q_j \log q_j \, dz_j + \text{const.}$$
  
=  $-D_{\text{KL}}(q_j(z) \| \tilde{p}(x, z_j)) + \text{const.}$ 

and maximize wrt.  $q_j$ . Doing so minimizes  $D_{KL}(q(z_j)||\tilde{p}(x, z_j))$ , thus the minimum is at  $q_i^*$  with

$$\log q_j^*(z_j) = \log \tilde{p}(x, z_j) = \mathbb{E}_{q, i \neq j}(\log p(x, z)) + \text{const.}$$
(\*)

**\triangleright** note that this expression identifies a **function**  $q_i$ , not some parametric form.

▶ the optimization converges, because  $-\mathcal{L}(q)$  can be shown to be *convex* wrt. q.

In physics, this trick is known as **mean field theory** (because an *n*-body problem is separated into *n* separate problems of individual particles who are affected by the "mean field"  $\tilde{p}$  summarizing the expected effect of all other particles).



#### Variational Inference

► is a general framework to construct approximating probability distributions q(z) to non-analytic posterior distributions p(z | x) by minimizing the functional

$$q^* = \arg\min_{q \in \mathcal{Q}} D_{KL}(q(z) \| p(z \mid x)) = \arg\max_{q \in \mathcal{Q}} \mathcal{L}(q)$$

- ▶ the beauty is that we get to *choose q*, so one can nearly always find a tractable approximation.
- ▶ If we impose the mean field approximation  $q(z) = \prod_i q(z_i)$ , get

 $\log q_j^*(z_j) = \mathbb{E}_{q,i\neq j}(\log p(x,z)) + \text{const.}.$ 

▶ for Exponential Family p things are particularly simple: we only need the expectation under q of the sufficient statistics.

Variational Inference is an extremely flexible and powerful approximation method. Its downside is that constructing the bound and update equations can be tedious. For a quick test, variational inference is often not a good idea. But for a deployed product, it can be the most powerful tool in the box.