



From Newton to Einstein: A guided tour through space and time

with Carla Cederbaum

Betelgeuse in Orion

Outline of our tour

Sir Isaac Newton 1643-1727

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3



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Ouch!

Ah!

Why are the planets orbiting the sun?

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ہر ار heavy

, inert

Why are the planets orbiting the sun? inert heavy,

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Newton's new math

- rate of change/derivative

$$f'(x_0) = \lim_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

- vectors: velocity, acceleration, force \vec{v} \vec{a} \vec{F}

Newton's law of gravity

m = mass of planet
M = mass of sun
G = gravitational constant
\$\vec{rr}\$ = distance planet to sun

$$\vec{F} = -\frac{mMG\vec{r}}{r^3}$$



How do we measure mass?



mass

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Transform Newton's ideas into math!

Modeling gravitation with mathematics (vector calculus) allows to compute predictions and improve understanding!

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Vector calculus

Idea: generalize calculus to 3-dimensional space!

$$f'(x_0) = \lim_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

$$\rightarrow \frac{\partial f}{\partial x}(x_0, y_0, z_0) = \lim_{x \to x_0} \frac{f(x, y_0, z_0) - f(x_0, y_0, z_0)}{x - x_0}$$



Newton's idea revisited

- U = Newtonian potential of sun
- G = gravitational constant
- p = mass density = mass/volume
- = "differential operator"

$$\triangle U = 4\pi G\rho$$





U = Newtonian potential of sun
m = mass of planet
▼ = a differential operator

$$\vec{F} = -m\vec{\nabla}U$$



What is now mass M? M = mass of sun $\vec{n} = normal vector to surface$





What is now mass M? Apply mathematical theorems (by Gauß and Stokes)

$$M = \iiint_{\text{sun}} \rho \, dV$$

= ...
= $\iint_{\text{surface of sun}} \vec{\nabla} U \cdot \vec{n} \, dS$



Summary

New math allows to - write Newton's ideas as "differential equation" $\Delta U = 4\pi G \rho$

 express mass as an integral (using mathematical theorems)

$$M = \iint_{\text{surface of sun}} \vec{\nabla} U \cdot \vec{n} \, dS$$



Morale

- Use new math to "model" gravitation mathematically.
 - -gives better methods for predictions
 - -helps understand gravity better
- Newton's new physics inspired new math!



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Carl Friedrich Gauß 1777-1855

Bernhard Riemann 1826-1866

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Curvature is important for:

- Geodesy and Geography
- Astronomy
- Physics
- Engineering (wings of planes,...)
- Biology (surface of cells,...)
- Mathematics

-> differential geometry

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Differential Geometry

 studies curves and surfaces
 generalizes vector calculus
 allows rigorous definition of curvature
 (in terms of derivatives)



Curvature

- Curves can be curved.
- Surfaces can be curved.
- 3-dimensional space can also be curved!
- Can even think about higher dimensional (curved) space!!



Outline of our tour

Siméon Denis Poisson 1781-1840

1879-1955

2

Sir Isaac Pierre Simon Newton Laplace 1643-1727 1749-1827

Albert Einstein

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Carl Friedrich

Bernhard Riemann

1777-1855

1826-1866

Gauß

Why are the planets orbiting the sun?

 $R_{ix} = 0.2$

Conflicts with observations and electrodynamics!

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Modeling gravitation with mathematics (differential geometry) allows to compute predictions and improve understanding!

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Math allows to make predictions like

• Black holes:

• Expansion of universe:

Gravitational waves?

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Expanding distance between galaxies



Einstein's theory

- is called "general relativity"
- uses ideas from differential geometry like curvature
- describes gravitational effects by a differential equation



General relativity

Main equation:

$$\operatorname{Ric} -\frac{1}{2} \operatorname{g} R = \frac{8\pi G}{c^4} \operatorname{T}$$

c = speed of light
R, Ric: measure curvature
g: measures distance
T: describes matter



Describes the world

Einstein's theory is consistent with many measurements:

- bending of light

....

- gravitational red shift

Applications

- <u>General Positioning System</u>
- satellites
- space travel

General relativity in every day life:

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General relativity in every day life: matter curves space-time

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General relativity in every day life:

rior

General relativity in every day life: curvature influences movement

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General relativity in every day life:

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Morale

- Again: Use math to model gravitation. — gives better methods for predictions
- -helps understand gravity better
- Gauß/Riemann's new math allows to predict new phyics!









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Pierre Simon

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Albert Einstein 1879-1955



Carl Friedrich Gauß 1777-1855

Bernhard Riemann 1826-1866

> Jürgen Ehlers 1929-2008

> > today

Naive Idea: Yes! Einstein's general relativity is much better (in predicting experiments) And much more beautiful!

Can we forget about Newton?

But: also more difficult!

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Can we forget about Newton?

Better: Reconcile the theories: Think of Newton's theory

as an approximation to Einstein's?

Also: Try to learn from <u>Newton's theory</u>

how to interpret relativistic notions!

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Example: What is mass in general relativity?

Negative mass?

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Many different definitions

At infinity?



My thesis: What is a good definition of relativistic mass?

Step 1: differential geometry + vector calculus = new formula for mass

Step 2: use Newtonian limit by to compare new definition with Newtonian mass

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Mass in general relativity

new formula for mass (analogy to Newtonian formula):

$$M = \iint \vec{\nabla} U \cdot \vec{n} \, dS$$
surface of sun

U, \vec{n} , dS, $\vec{\nabla}$ constructed from geometry

Newtonian limit

Newton's theory: c=infinite Einstein's theory: c=300.000km/s

Newtonian limit: take c to infinity



My thesis: When is relativistic mass approximatively Newtonian mass? Result: When a star or galaxy

does not move



0 m/h

then its relativistic mass is approximately equal to its Newtonian mass.

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My theorem

Theorem 6.4.1 (Newtonian Limit of Mass Theorem). Let $\mathcal{F}(\lambda) := (\mathbb{R} \times E^3, s^{\alpha\beta}(\lambda), t_{\alpha\beta}(\lambda), \Gamma^{\mu}_{\alpha\beta}(\lambda), T^{\alpha\beta}(\lambda), \lambda)$ be a family of static isolated ends in frame theory parametrized by $\lambda \in (0, \varepsilon)$ for some $\varepsilon > 0$ and let $\mathcal{F}(0) := (\mathbb{R} \times E^3, s^{\alpha\beta}(0), t_{\alpha\beta}(0), \Gamma^{\mu}_{\alpha\beta}(0), T^{\alpha\beta}(0), 0)$ be a static isolated system of FT with global Cartesian coordinates $(x^k(0))$. Assume that there exist global asymptotically flat systems of coordinates $(x^k(\lambda))$ for $\mathcal{F}(\lambda)$ converging to $(x^k(0))$ uniformly on M^3 as $\lambda \to 0$. Let ${}^3g_{ij}(\lambda), \gamma_{ij}(\lambda), \gamma_{ij}(0), U(\lambda)$, and U(0) denote the physical and pseudo-Newtonian metrics and potentials of $\mathcal{F}(\lambda)$ and $\mathcal{F}(0)$, respectively. Then

 $m_{ADM}({}^{3}g(\lambda)) = m_{PNFT}(\gamma(\lambda), U(\lambda)) \rightarrow m_{PNFT}(\gamma(0), U(0)) = m_{N}(U(0))$

as $\lambda \rightarrow 0$.

What is the Newtonian Limit?

See movie

Orion

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- www.wikipedia.org
- www.myflyprofile.com
- www2.ed.gov
 - www.universe-review.ca
 - www.newscientist.com
 - www.flickr.com/photos/ak42/2971239293
- www.beyonddieting.com

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