



## **An SDN Architecture for Automotive Ethernets**

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- ▶ Motivation
- ▶ Evolution of E/E-Architectures
- ▶ Use Cases
  - Trailer Networks
  - Driver Assistance Systems
- ▶ Architecture
  - Overview
  - Data Plane
  - Management
- ▶ Operations
  - TSN Configuration
  - Discovery
  - Failover
- ▶ Security



- ▶ In-vehicle networks today
  - Low bandwidth technologies
  - Static configuration, determined during manufacturing
  
- ▶ Future
  - More bandwidth demand
  - Configuration changes after purchase
    - Plug-and-play add-on components
    - Downloadable features
  
- ▶ Reconfigurable networks required



- ▶ Distributed ECUs connected to single CAN bus
- ▶ Multiple CAN buses connected to central gateway
  - Additional application specific buses (LIN, MOST, FlexRay)
- ▶ Consolidation of functionality into more powerful devices
  - Domain model
    - ECUs separated into Domains (safety, comfort, infotainment,...)
    - One or more buses per domain connected to domain controller
    - Domain controllers connected by backbone network
    - Problem: wiring effort
  - Zone model
    - Zone controllers per location (front left/right, rear left/right,...)
    - ECUs connected to local zone controllers
    - Zone controllers interconnected by backbone network (mesh)
- ▶ Automotive Ethernet
- ▶ Time Sensitive Networking



# Use Case: Trailer Networks

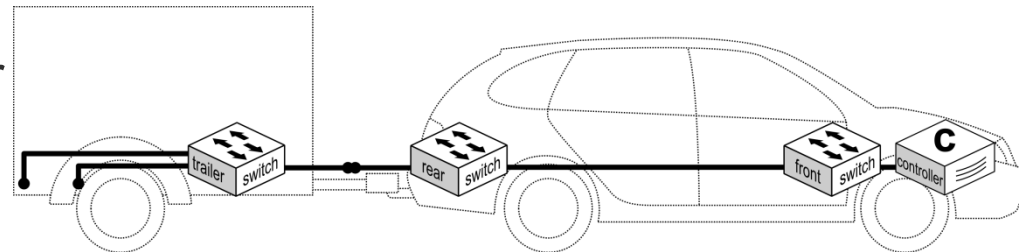
## ▶ Trailer connection today

- Electrical connection (5-22 pins)
- Fixed function set (tail lamps, turn signals, electric brakes)



## ▶ Future

- Switches in car and trailer
- Ethernet connection



## ▶ Benefits from reconfigurable networks

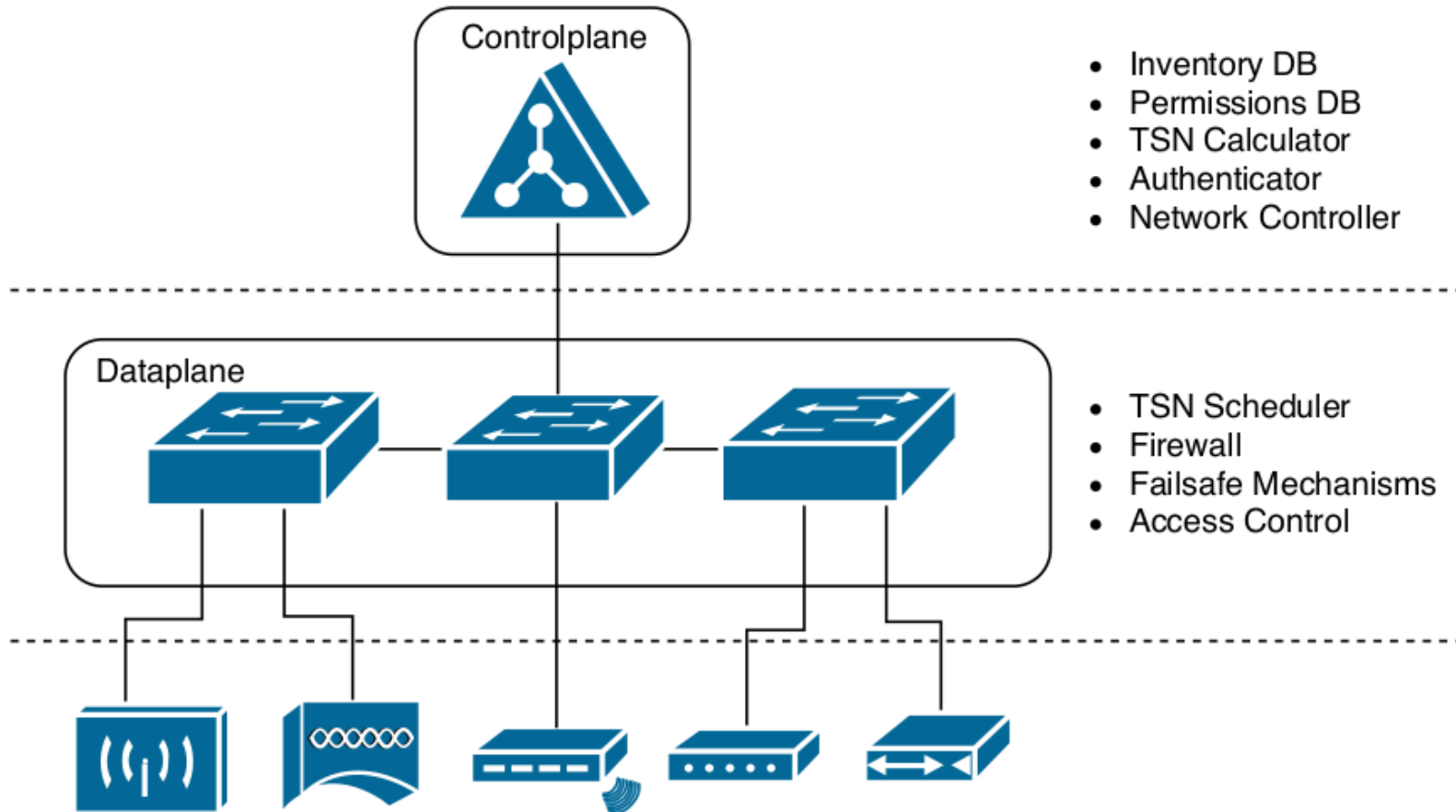
- Connection of networked components in trailer to vehicle
  - Cameras
  - Sensors (e.g., park distance control)
  - Actuators (e.g. electric brakes with TSN)
- Sharing of uplink (e.g., Wi-Fi for caravans/camping trailers)



- ▶ Downloadable driver-assistance systems or OTA updates
  
- ▶ Benefits from reconfigurable networks
  - Change of data sources (sensors, etc.)
  - Reconfiguration of real-time streams
  
- ▶ Example: Update of collision avoidance system
  - Initial feature set
    - Check forward traffic only
  - Update
    - Check backward traffic while reversing
  - Needs access to reversing camera or PDC sensors
  - Re-configuration of network required



# Automotive SDN Architecture





## ► Components

- Scheduler
- Rate limiter
- Firewall
- Fail-safe mechanisms
- Redundant links
- Access control

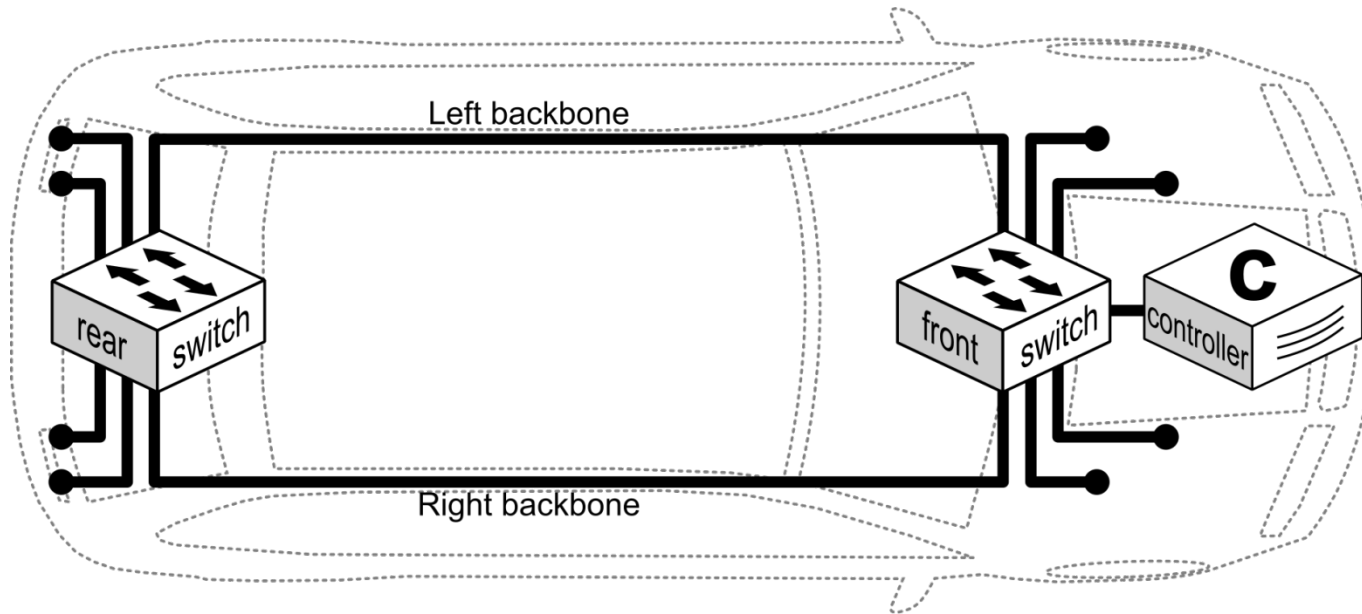
## ► Functionality

- Interconnect components and applications
- Connect components and applications to management system

## ► Traffic classes

- Hard real-time
  - Safety-critical components
  - Fixed deadlines
- Soft real-time
  - Less critical systems
  - Degraded operation possible with missed deadlines
- Configuration
  - Management
  - Discovery
- Best effort
  - Infotainment
  - All other traffic

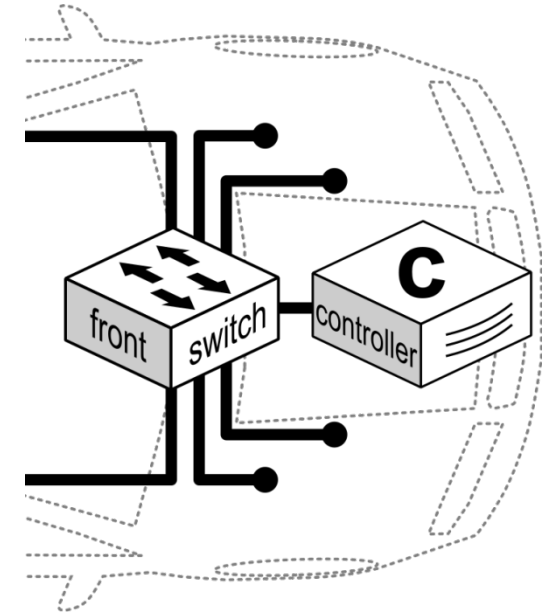




- ▶ Two switches (front and rear switch)
- ▶ Two backbone links between front and rear
  - Link aggregation during normal operation
  - Rescheduling traffic to the operational link in case of link failure
  - 1+1 protection for selected critical flows



- ▶ Data plane configured by network controller
- ▶ Controller Directly connected to one of the switches
- ▶ In-band signaling
  - Reduced wiring effort
  - Extensibility (trailer use case)
- ▶ Northbound interface
  - Used to trigger reconfigurations
  - Access restricted by ACLs and permission levels





- ▶ Safety critical components require real-time communication
- ▶ Updates of Time Sensitive Networking (TSN) configuration
  - Allocation of bandwidth
  - Re-calculation of schedules
  - Path selection for 1+1 protection
- ▶ Hybrid scheduling
  - In-car controller calculates initial schedule
    - Guarantees for safety-critical systems
    - Non-optimal, with approximations
  - Cloud service is triggered for schedule calculation
    - Re-use cached schedule for same constellation
    - Compute optimal schedule if no cached schedule available



- ▶ Discovery of devices based on signed manifest
  - Network ports of switches blocked initially, only discovery channel open
  - New device sends manifest via broadcast message on discovery channel
    - Contains information about device (identification, requirements to network, access to northbound API of controller required, ...)
    - Signed by manufacturer of device
    - External store of CA certificates, local cache
  - Controller re-configures network, gives access to northbound API if requirements of device are not static (e.g. if apps can be installed)
- ▶ Application discovery similar
  - Difference: Manifest sent by Host device via northbound API



- ▶ Single backbone link failure
  - Traffic is rerouted through remaining backbone link
  - Pre-calculated outage schedule for TSN flows
- ▶ Controller failure
  - No reconfiguration possible anymore
  - Backup flows and schedules pre-computed for critical systems
  - Switches apply backup configuration if connection to controller lost
- ▶ Switch failure or double backbone link failure
  - Components enter fail-safe state
  - Backup systems to ensure safe stop of vehicle



## ▶ Devices and Applications

- New devices can only access network for discovery
- Manifest signed by trusted manufacturer required
- Device sends app manifest to controller via northbound API
- Central CA store contains CA certificates

## ▶ Network security

- Specific flows between devices and applications
- Firewall for outside connections
  - Filtering of uplink, V2X, Bluetooth, Wi-Fi
- MACsec or AUTOSAR SecOc for integrity protection
- Access restrictions for controller interfaces



- ▶ Legacy automotive networks
  - Low bandwidth
  - Static configuration
- ▶ New applications and use cases
  - Higher bandwidth demand
  - More flexibility needed
- ▶ Technology for future automotive networks
  - Automotive Ethernet
  - Time-Sensitive Networking
- ▶ SDN concepts for automotive ethernets
  - Configuration and management
  - Path selection
  - TSN Schedules
  - Access Control



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